Sixth Sense Omnidirectional Drone Detection (SSODD)



Josh Lehman Dominic Keene Will Covington Danny Mullen



Background

- Increased drone usage in the modern battlefield
- Quality and sophistication greatly vary
- Used for surveillance and demolition, often in tandem
- US Armed Forces currently have no reliable way to dynamically detect small UAVs



Our Challenge

Develop a UMS early warning or deterrence system – could the solution be wearable?



Our Solution

- Detect incoming RF and audio
- Quickly process data to determine a threat level
- At a high enough threat level, administer an electronic stimulus
- Emulate the sensation of the hair on your neck standing up



Demonstrated Features

- Directional RF Detection of Drones
- Directional Audio Frequency Analysis-based detection of drones
- RF signal processing
- Weighted algorithm output indicating likelihood of incoming drone
- Analog sensory stimulus to provide warning of incoming drones



Available Technologies

• There are a range of available technologies which we plan to leverage in our design



Sponsors & Stakeholders







Path Forward / Timeline



- Board Design
- Preliminary Testing of part compatibility

- System and Processing Algorithm Design
- Testing...
- Improve system
 design
- Possible component
 improvements
- Get permission to fly drones on campus





